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control of robot manipulators. It uses an elegant set of mathematical tools that emphasizes the geometry of robot motion and allows a large class of robotic manipulation problems to be analyzed within a unified framework.

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The main course text is: R.M. Murray, Z. Li, and S. Sastry, A Mathematical Introduction to Robotic Manipulation, CR Press, 1994. The 1st edition of this book is available freely on-line at the link above, and is perfectly adequate for the course We will refer to this text as MLS (the initials of the authors last names).

ME115 2016 - Robotics

This course will introduce the students to the mathematical and algorithmic foundations for modern robotics. Topics include rigid body motion, forward and inverse kinematics, trajectory generation, robot dynamics and control. The assignments will involve mathematical derivations/proofs and nontrivial programming in Robotic Operating Systems (ROS).

Introduction to Robotics (Class website) Ohio State ...

Human-Like Biomechanics is a comprehensive introduction into modern geometrical methods to be used as a unified research

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approach in two apparently separate and rapidly growing fields: mathematical biomechanics and humanoid robotics. The book contains six Chapters and an Appendix.

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This chapter provides an overview of the aeroassist technologies and performances for Mars missions. We review the current state-of-the-art aeroassist technologies for Mars explorations, including aerocapture, aerobraking, and entry. Then we present a parametric analysis considering key design parameters such as interplanetary trajectory and vehicle design parameters (lift-to-drag ratio ...

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